
JEHU 2

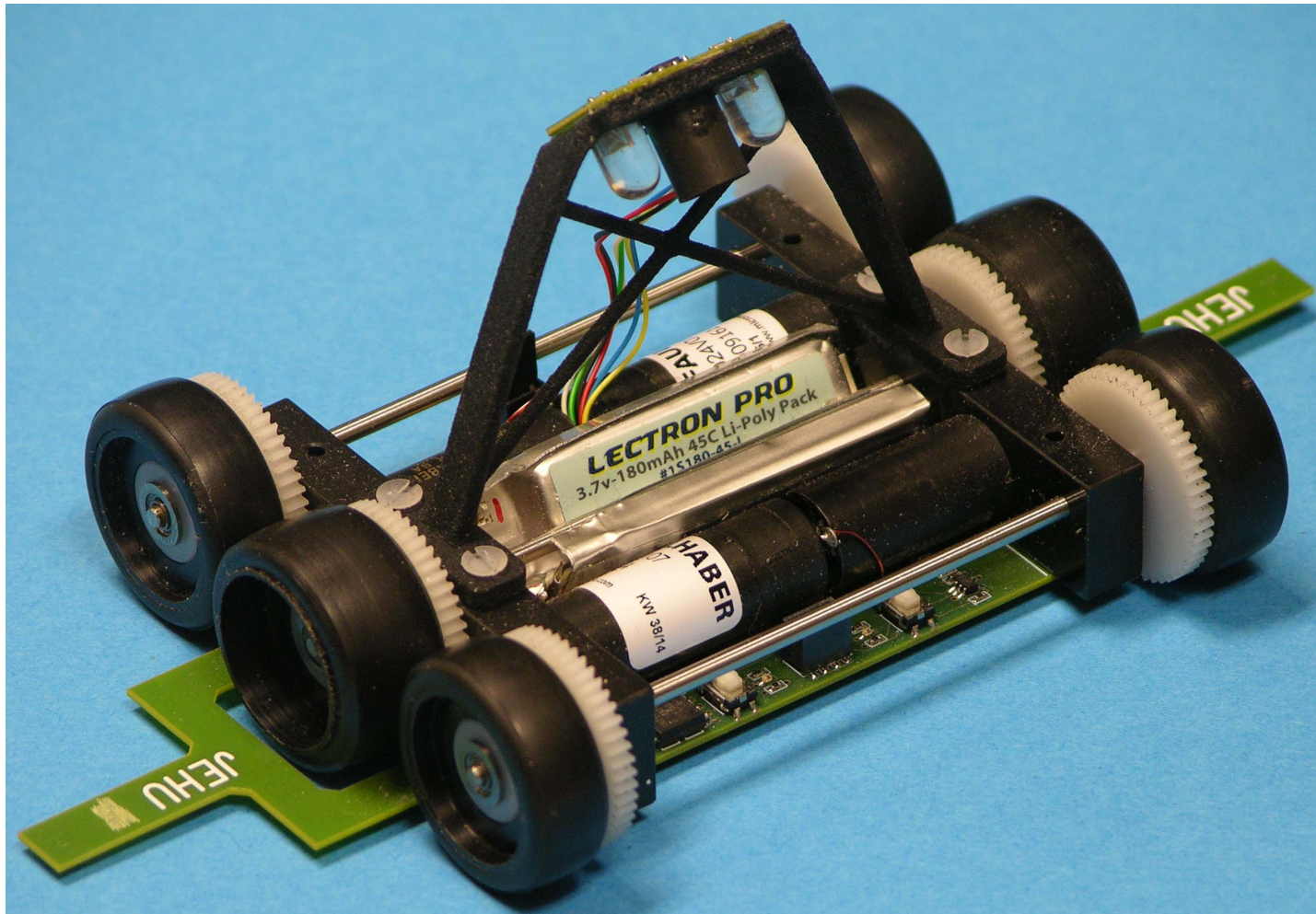
MINOS '18

Birmingham

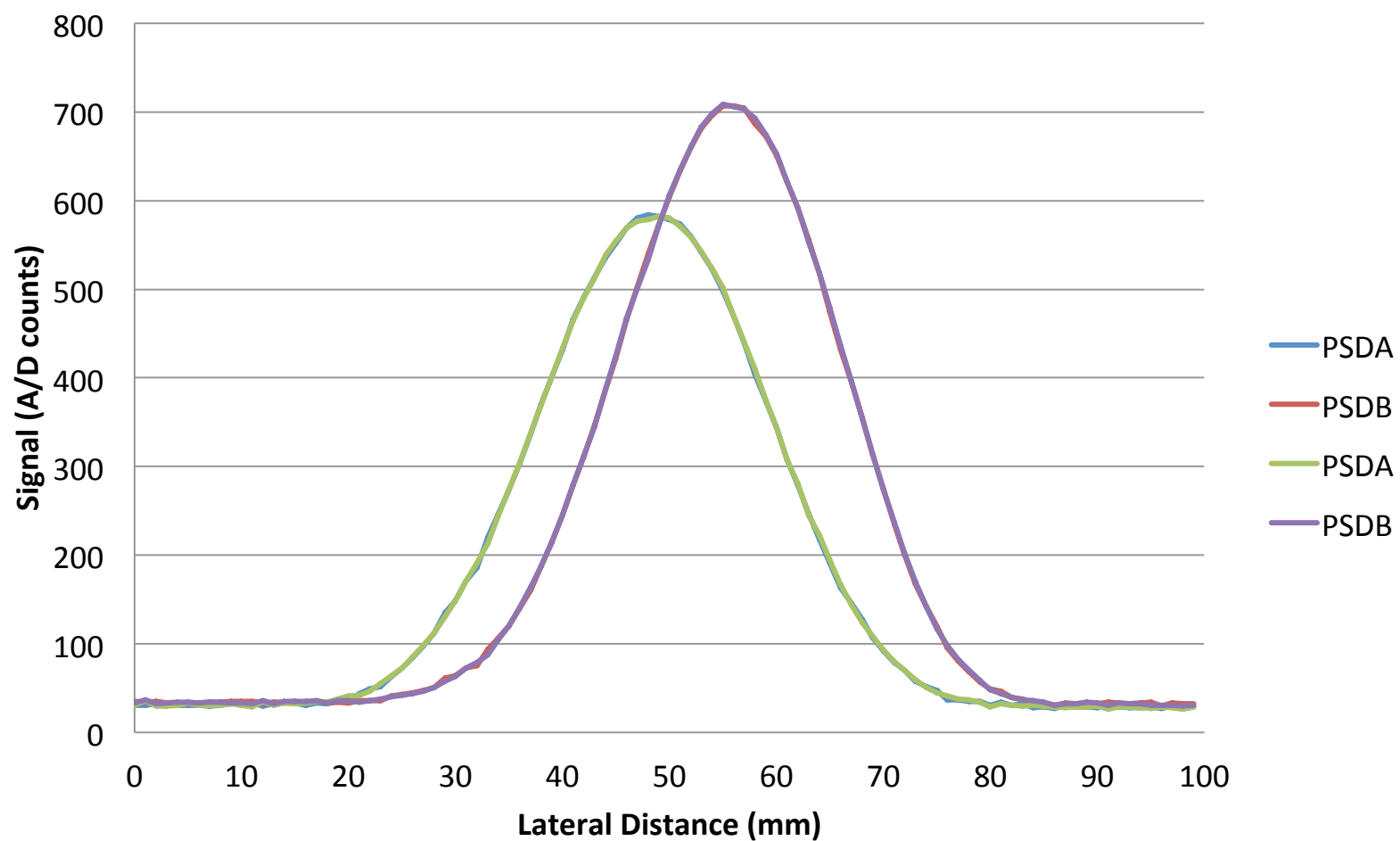
David Otten



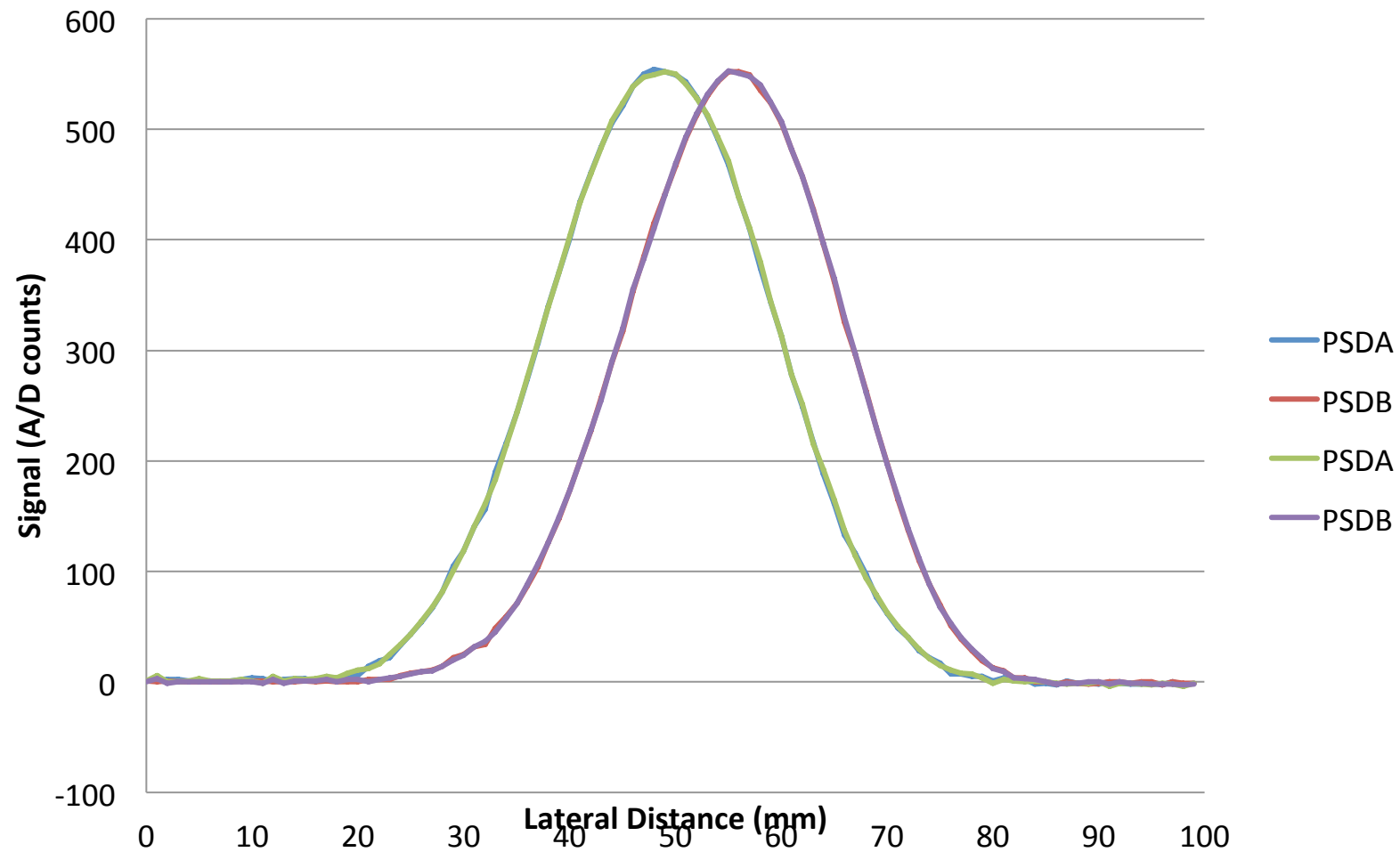
Jehu 3



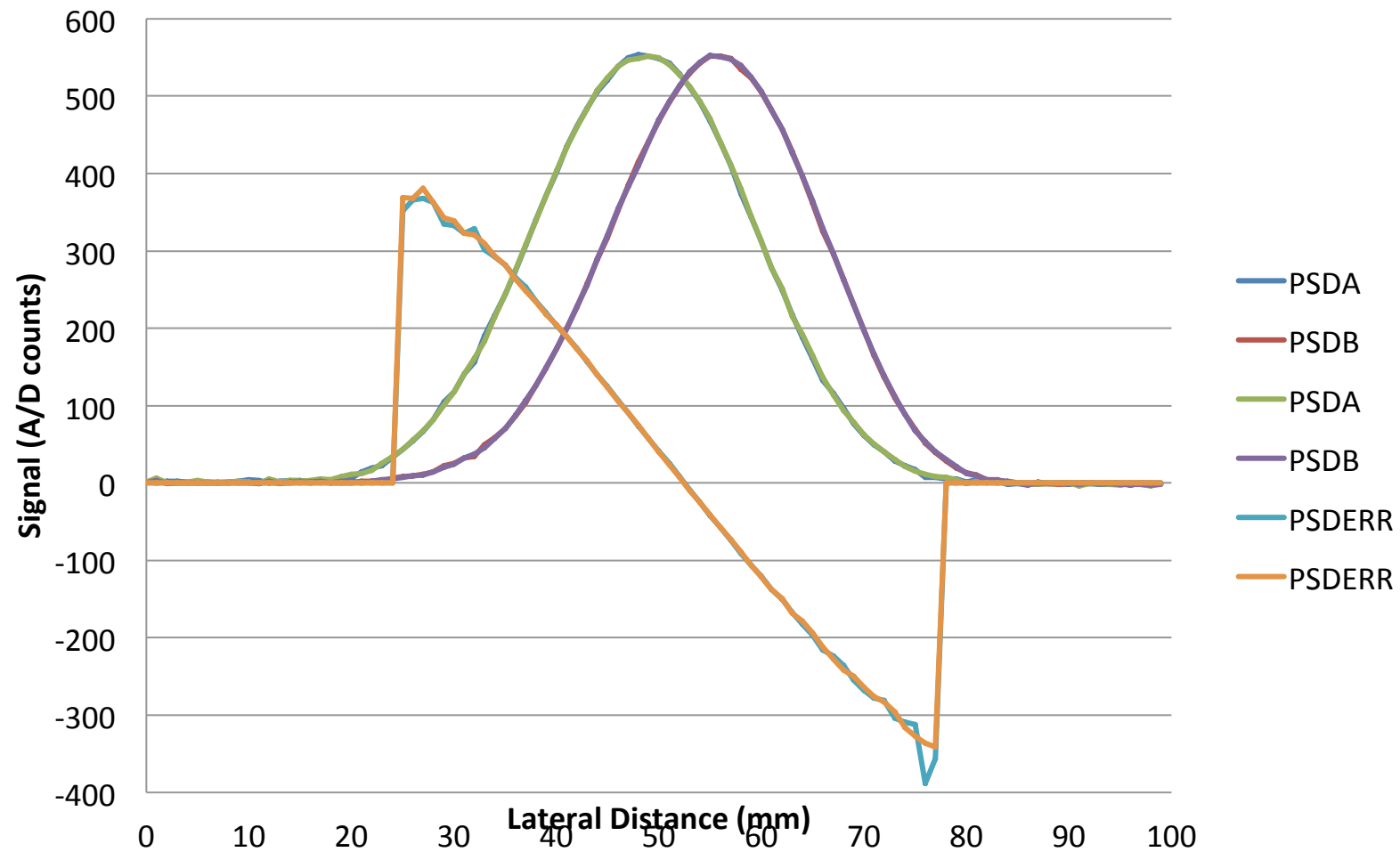
Jehu 3 PSD Signal



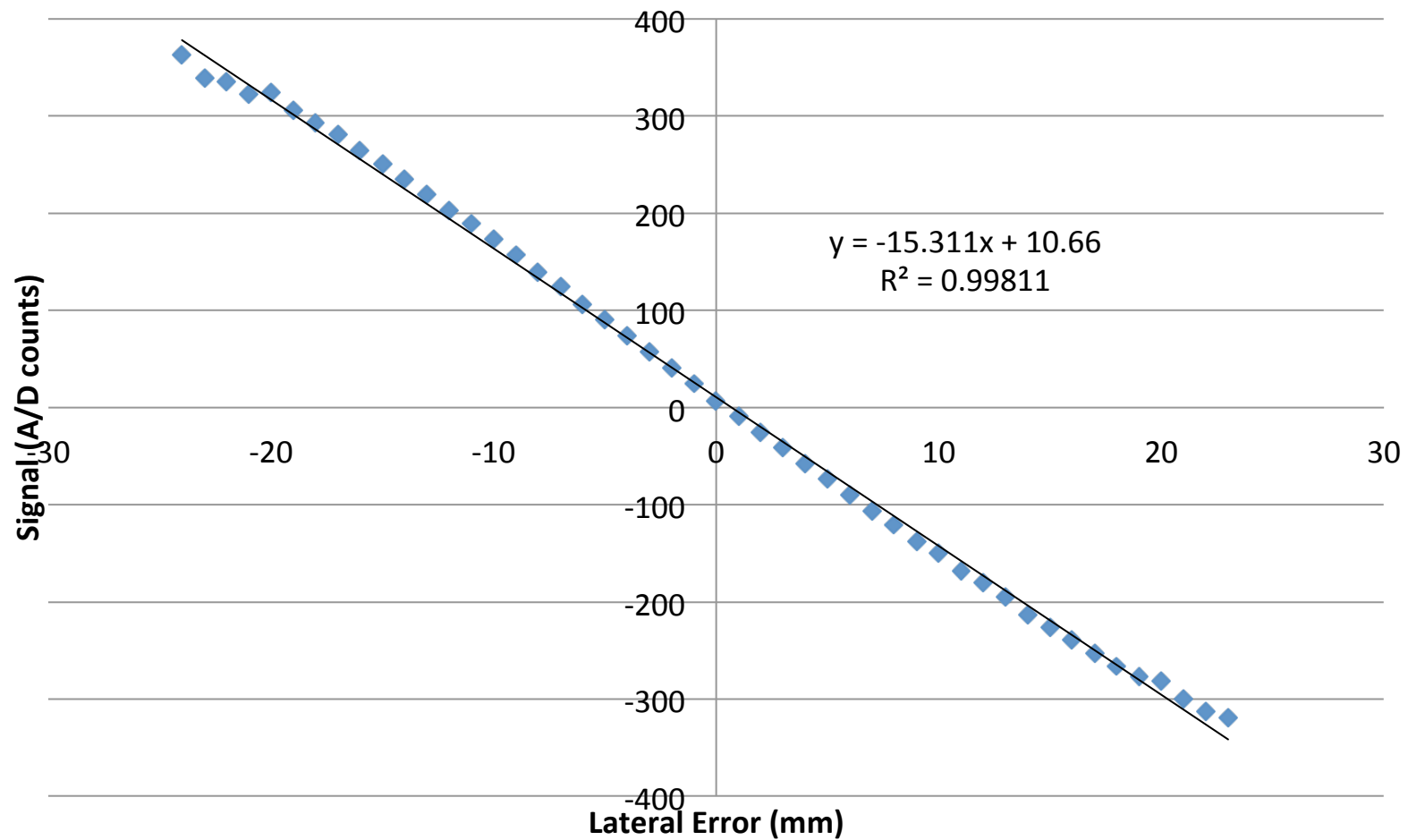
Offset and Amplitude Corrected



$1024 * \text{PSDB} / (\text{PSDA} + \text{PSDB}) - 512$

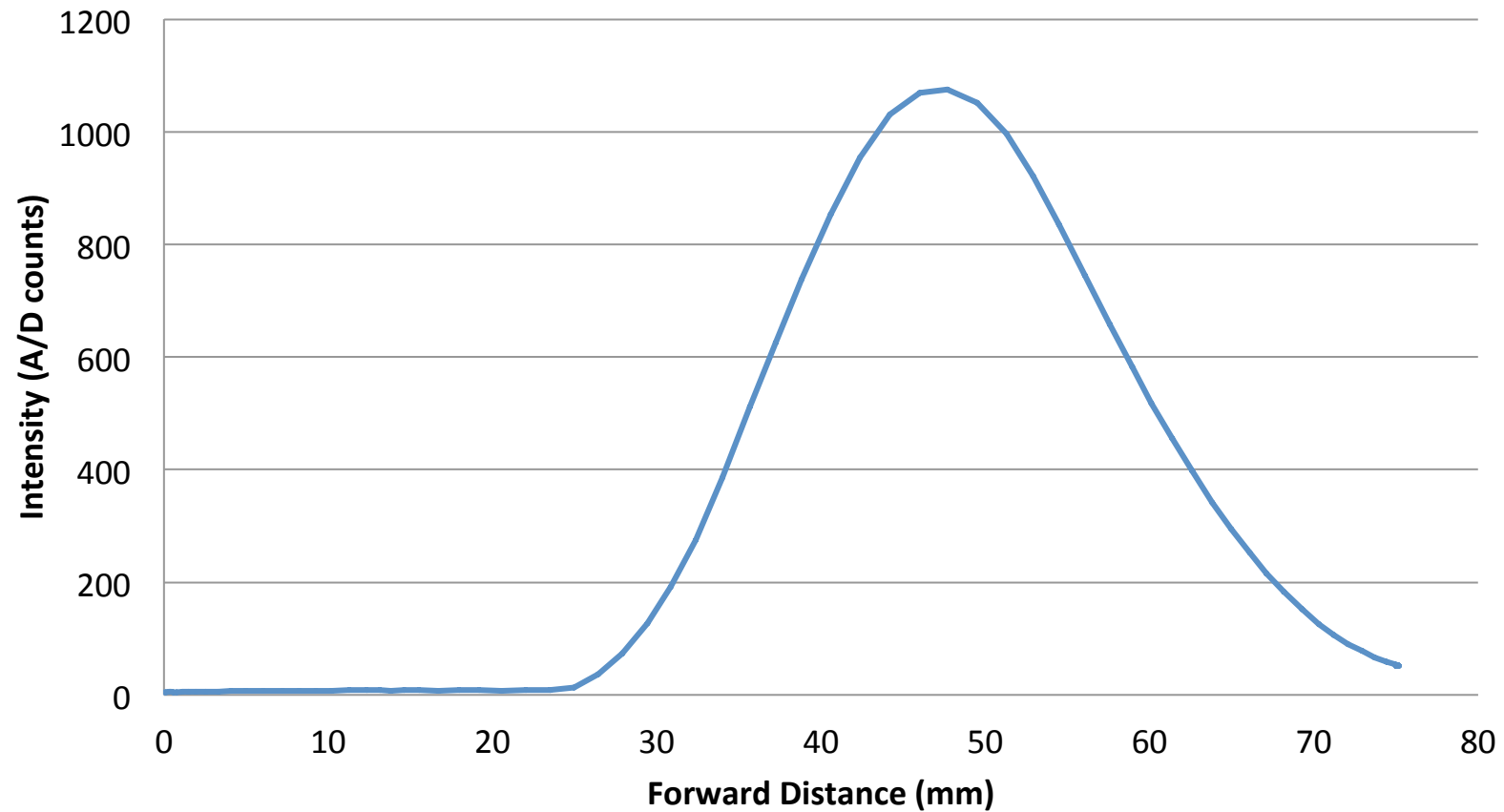


Sensor Gain and Linearity

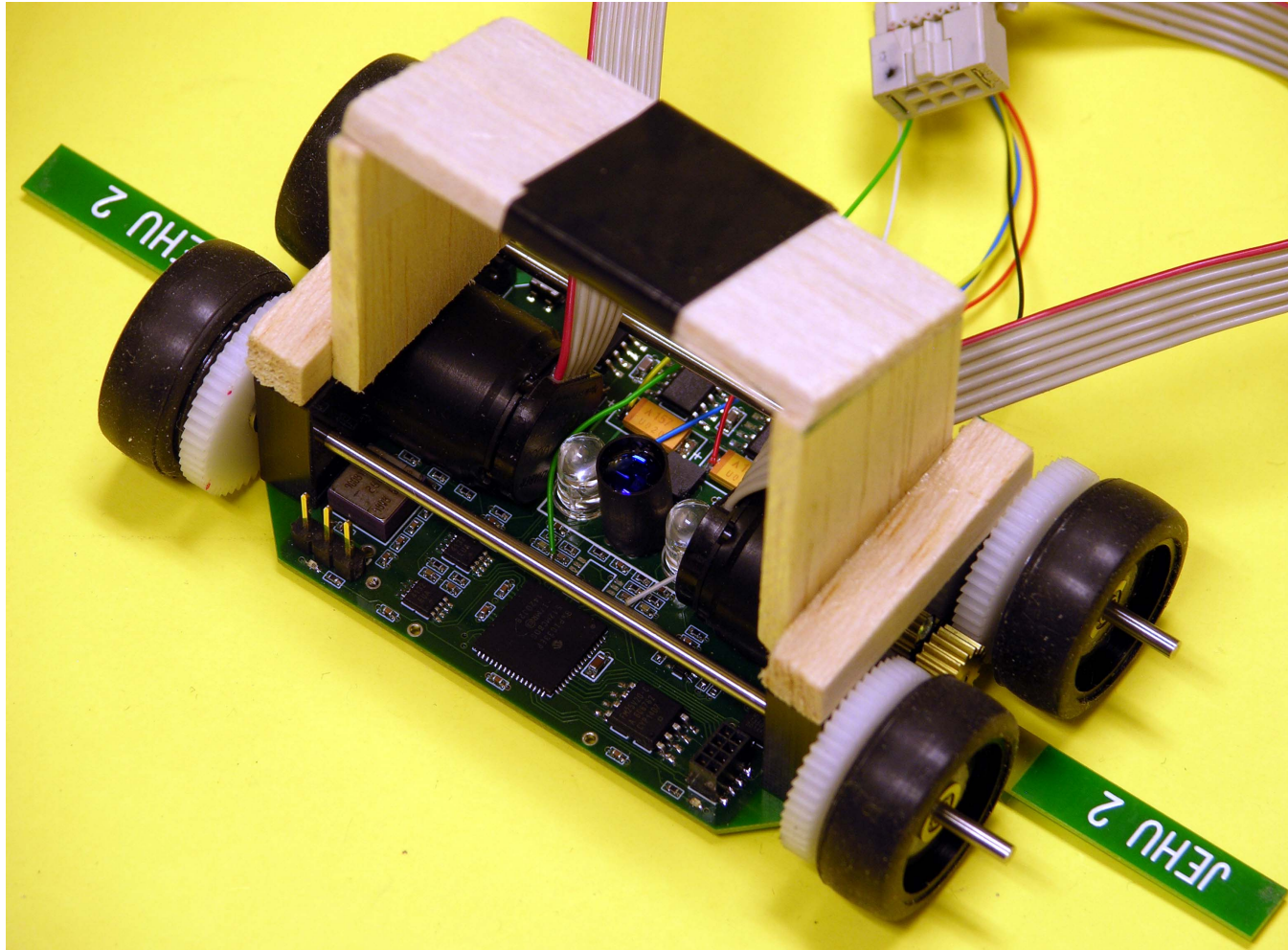


Intensity vs. Distance

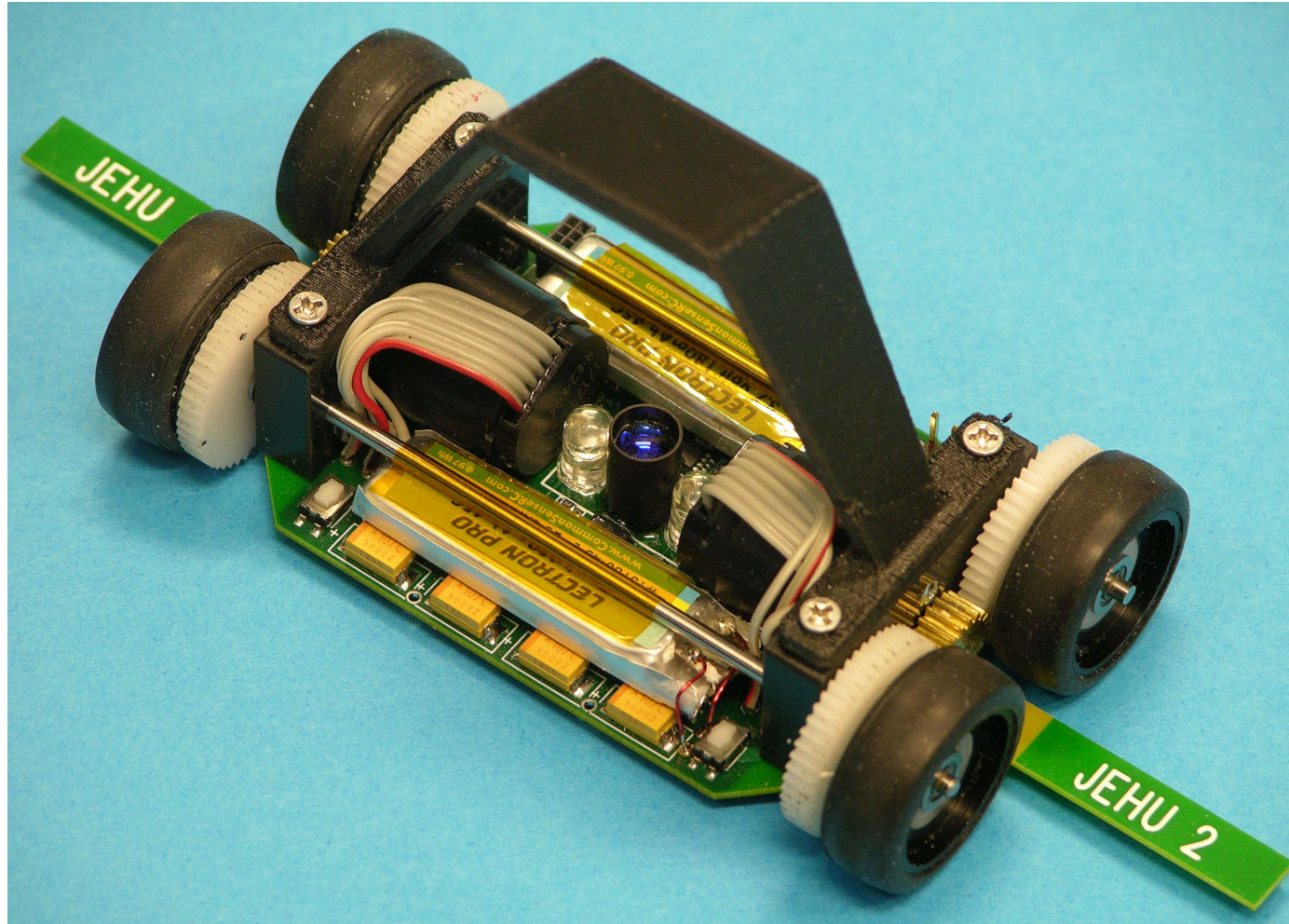
Peak = 46.7 mm (1.84")



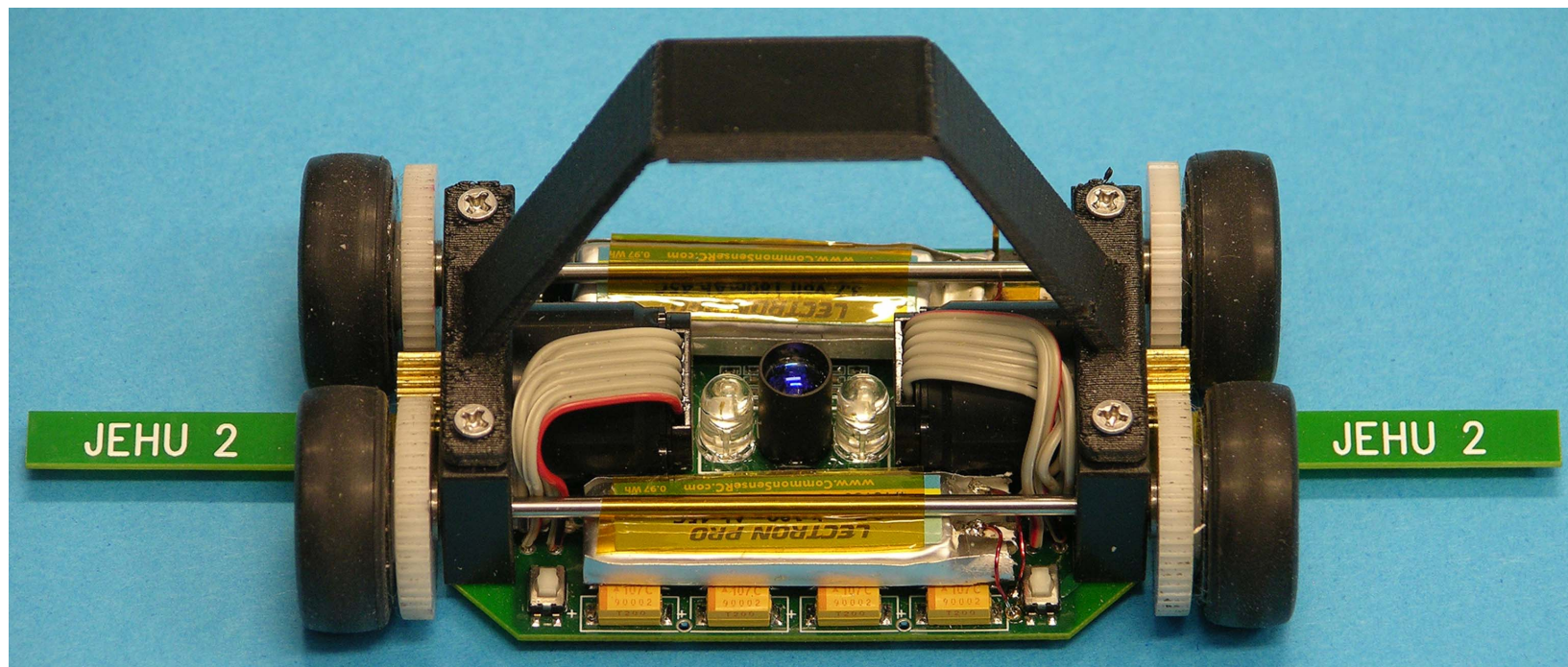
Jehu 2



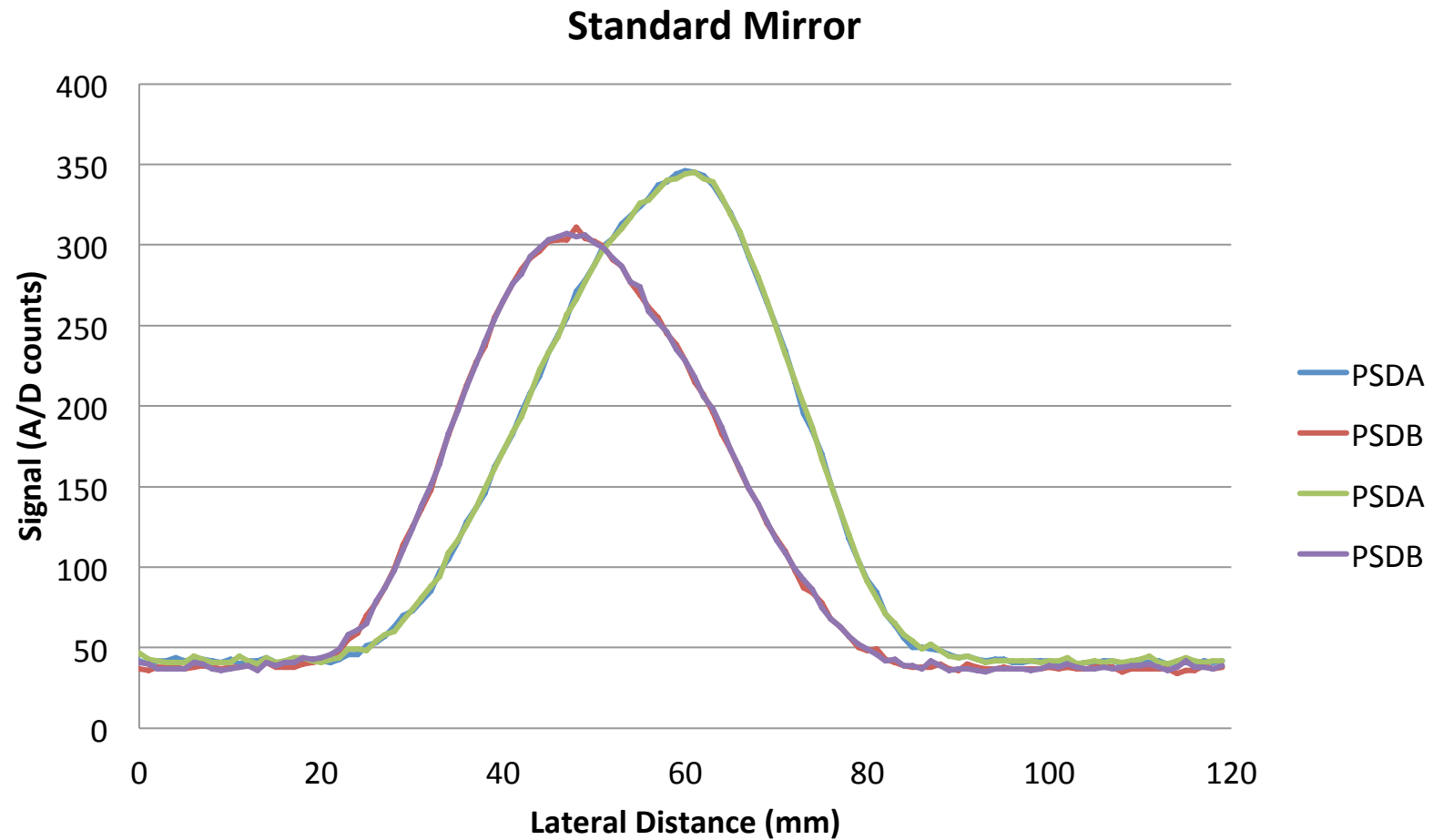
Front Corner View



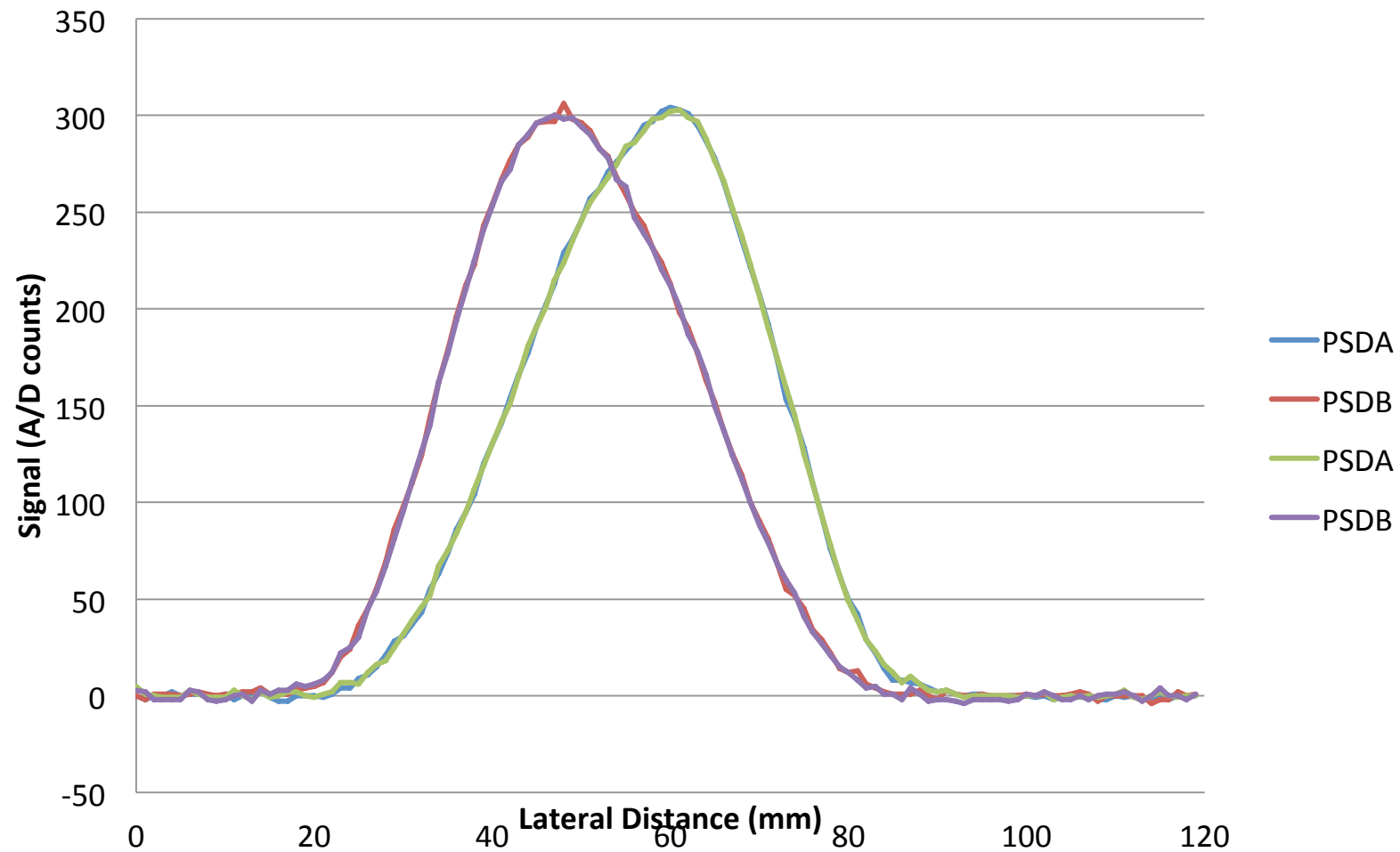
Front View



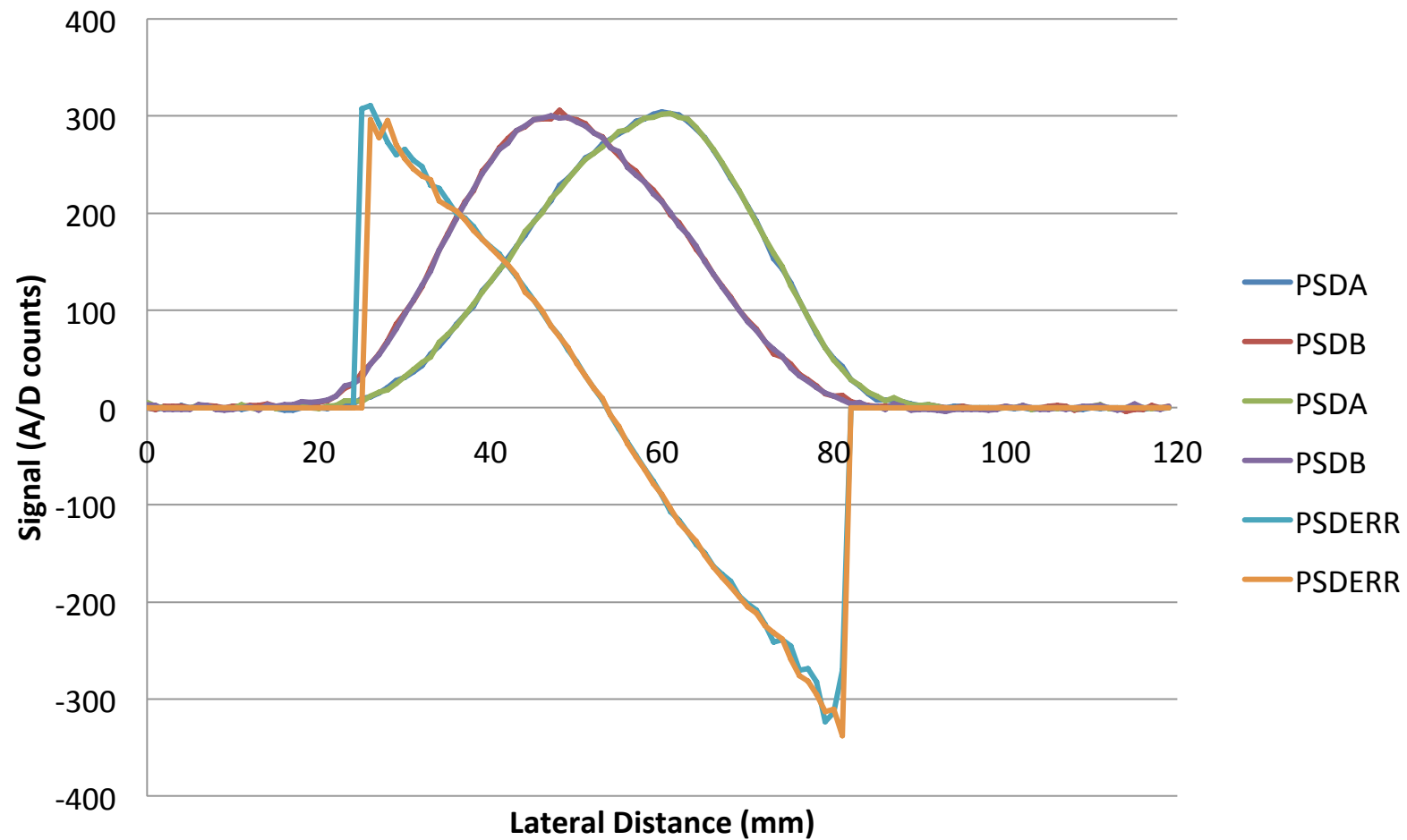
Jehu 3 PSD Signal



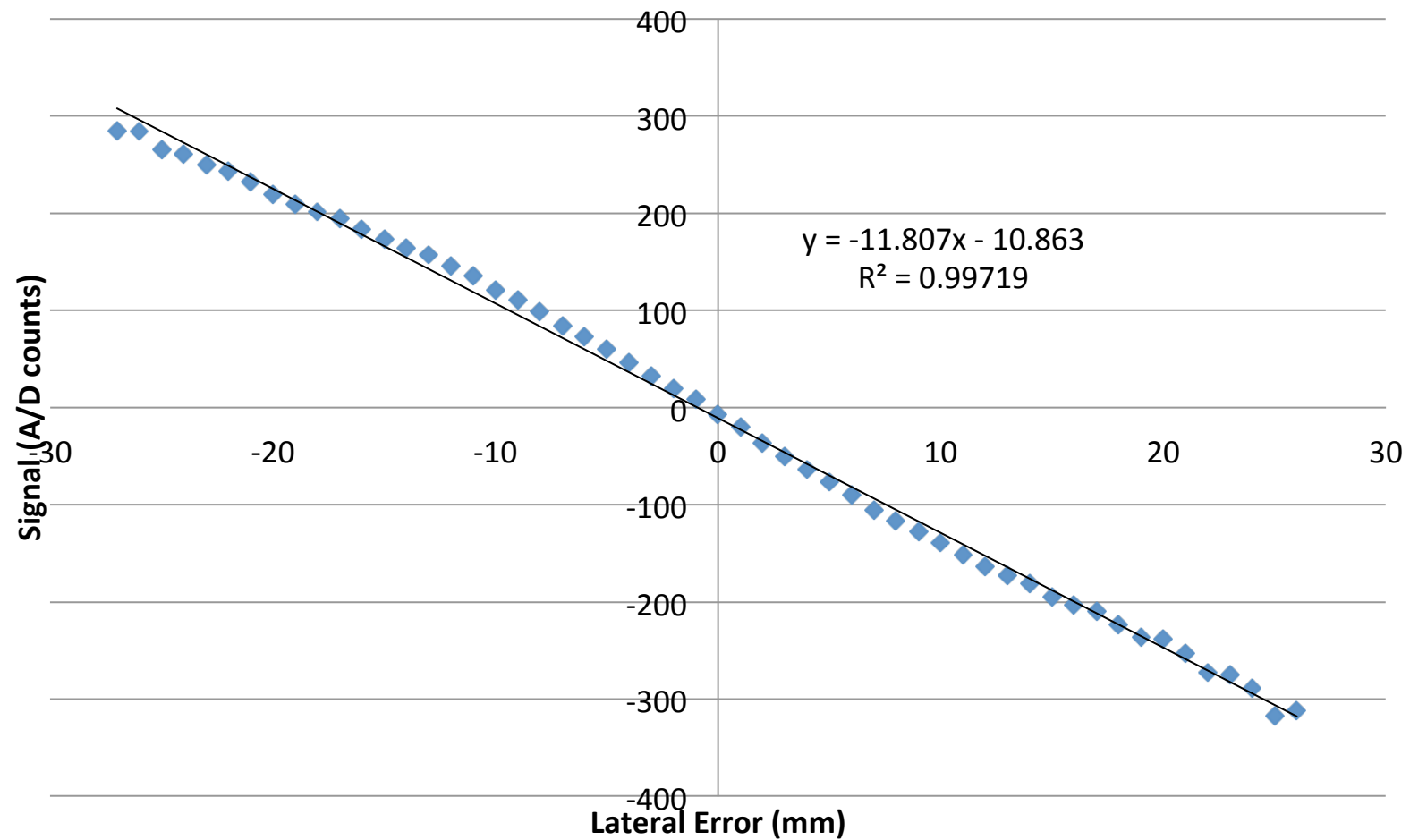
Offset and Amplitude Corrected



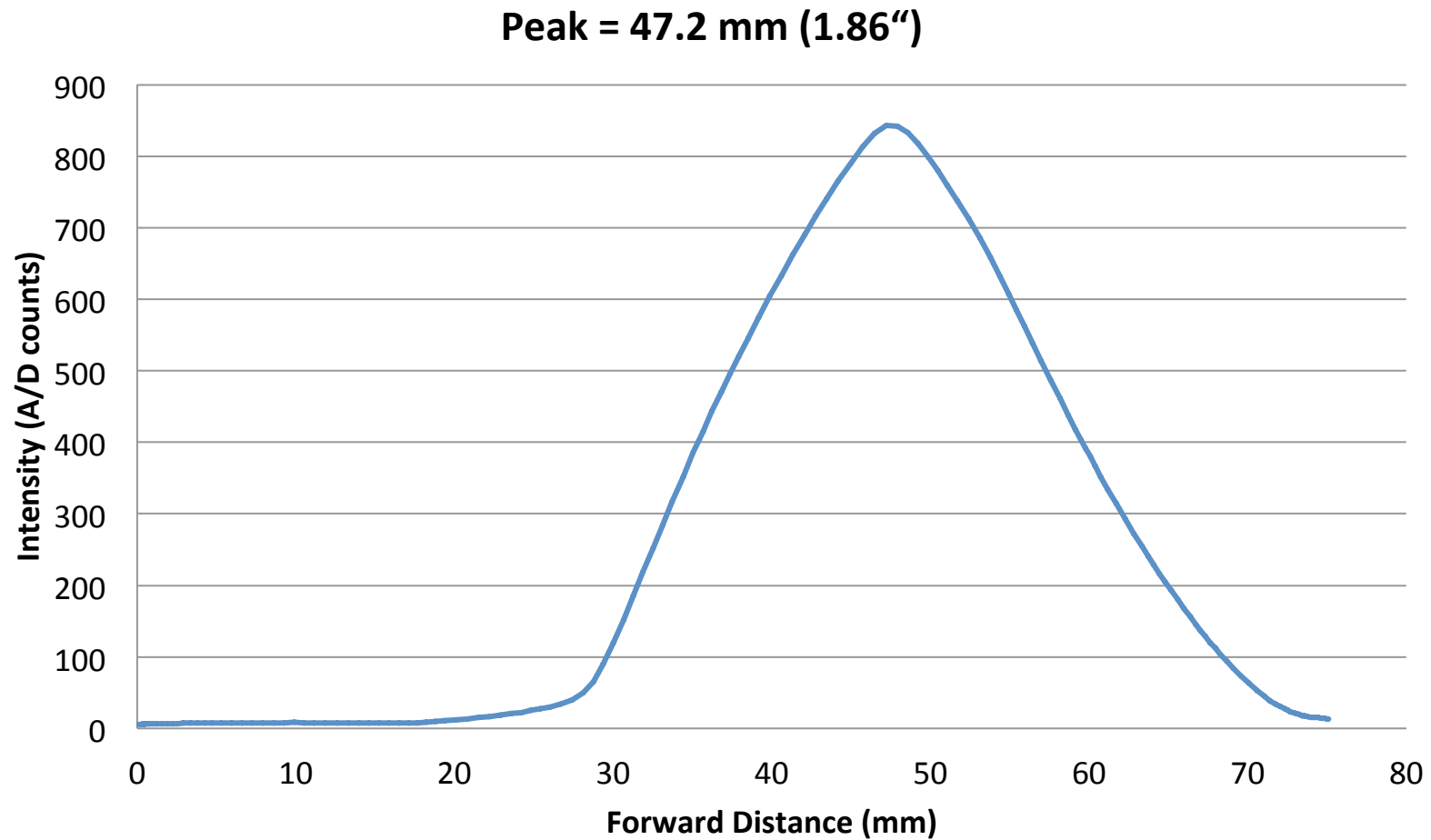
$$1024 * \text{PSDB} / (\text{PSDA} + \text{PSDB}) - 512$$



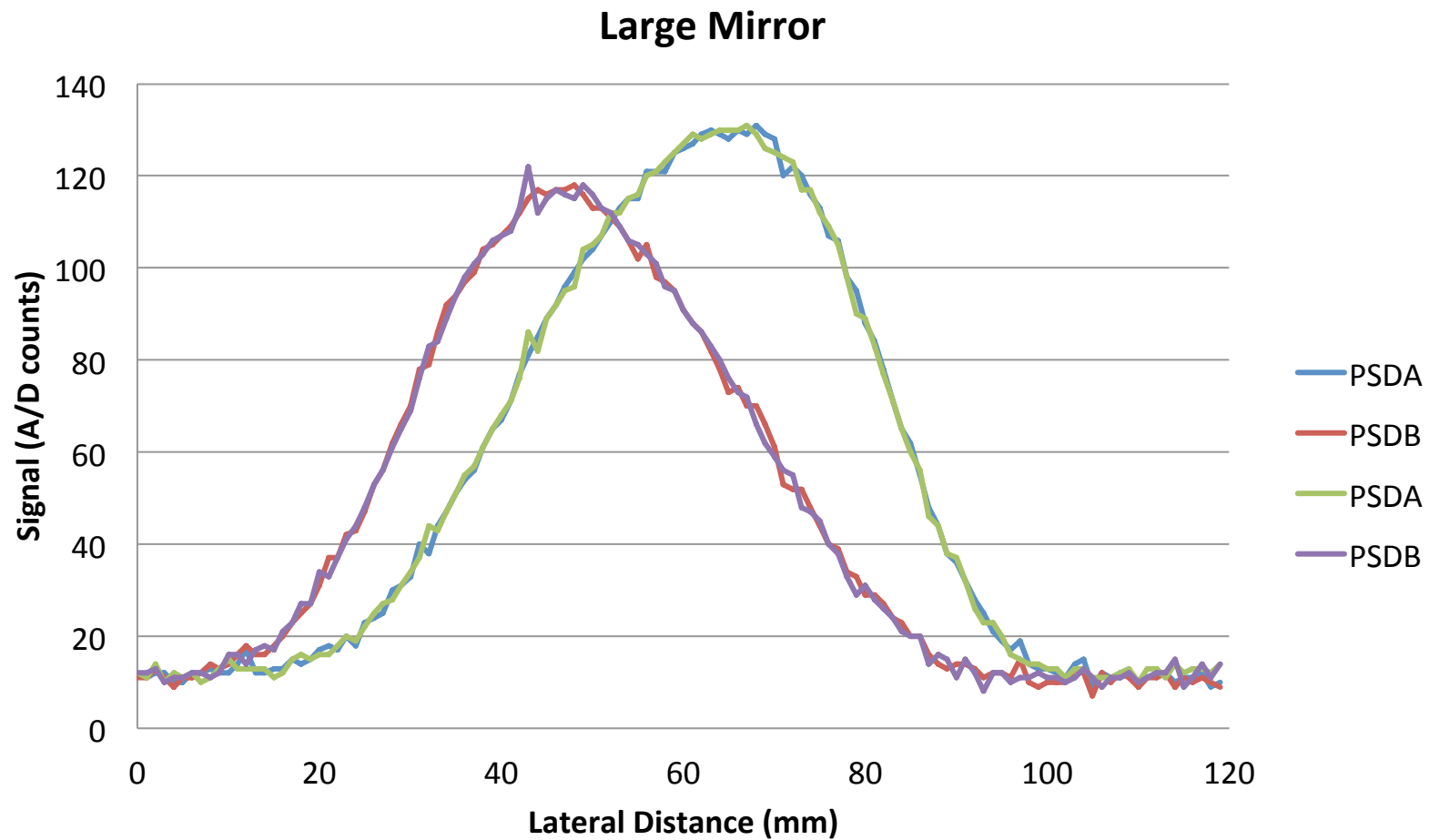
Sensor Gain and Linearity



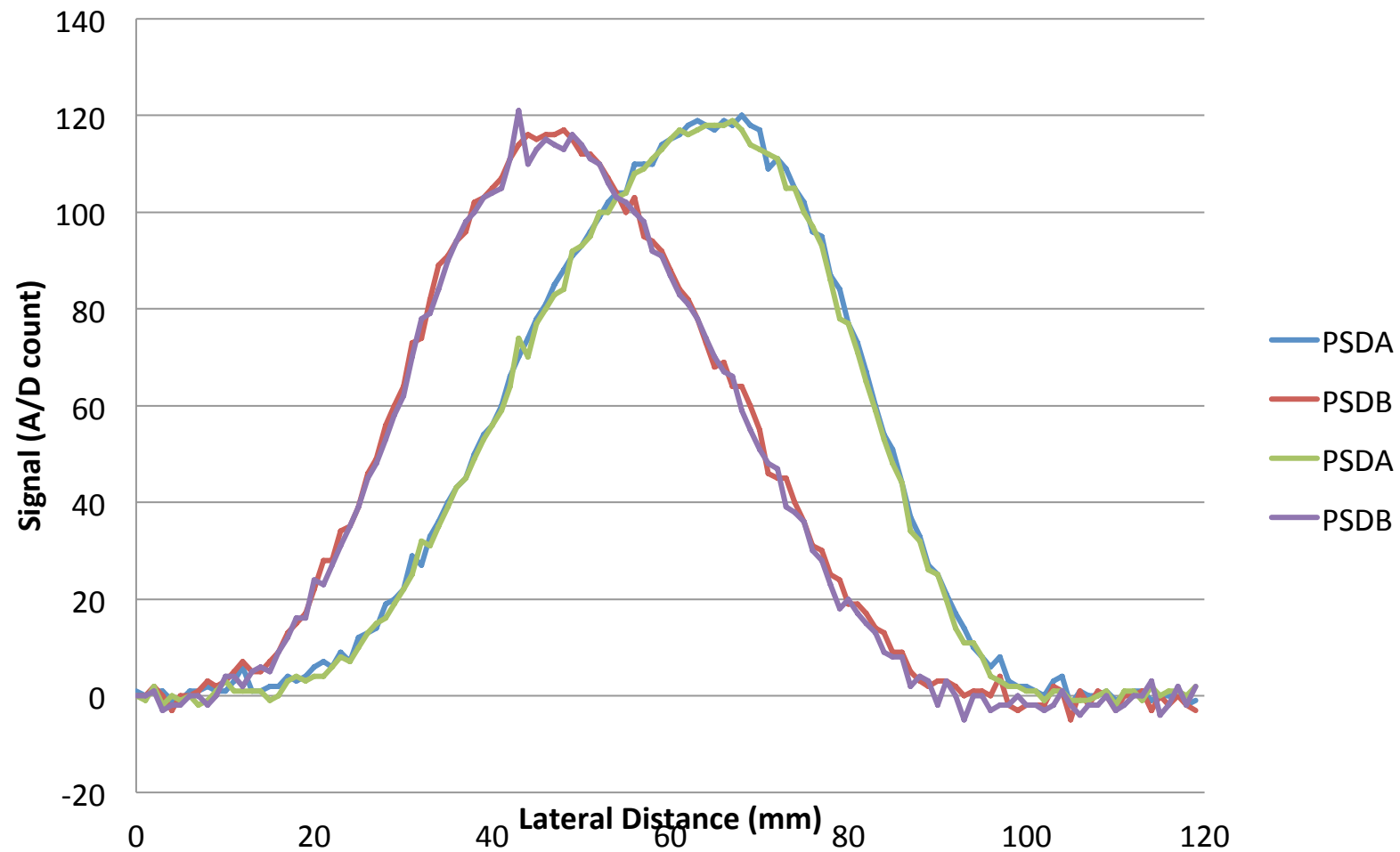
Intensity vs. Distance



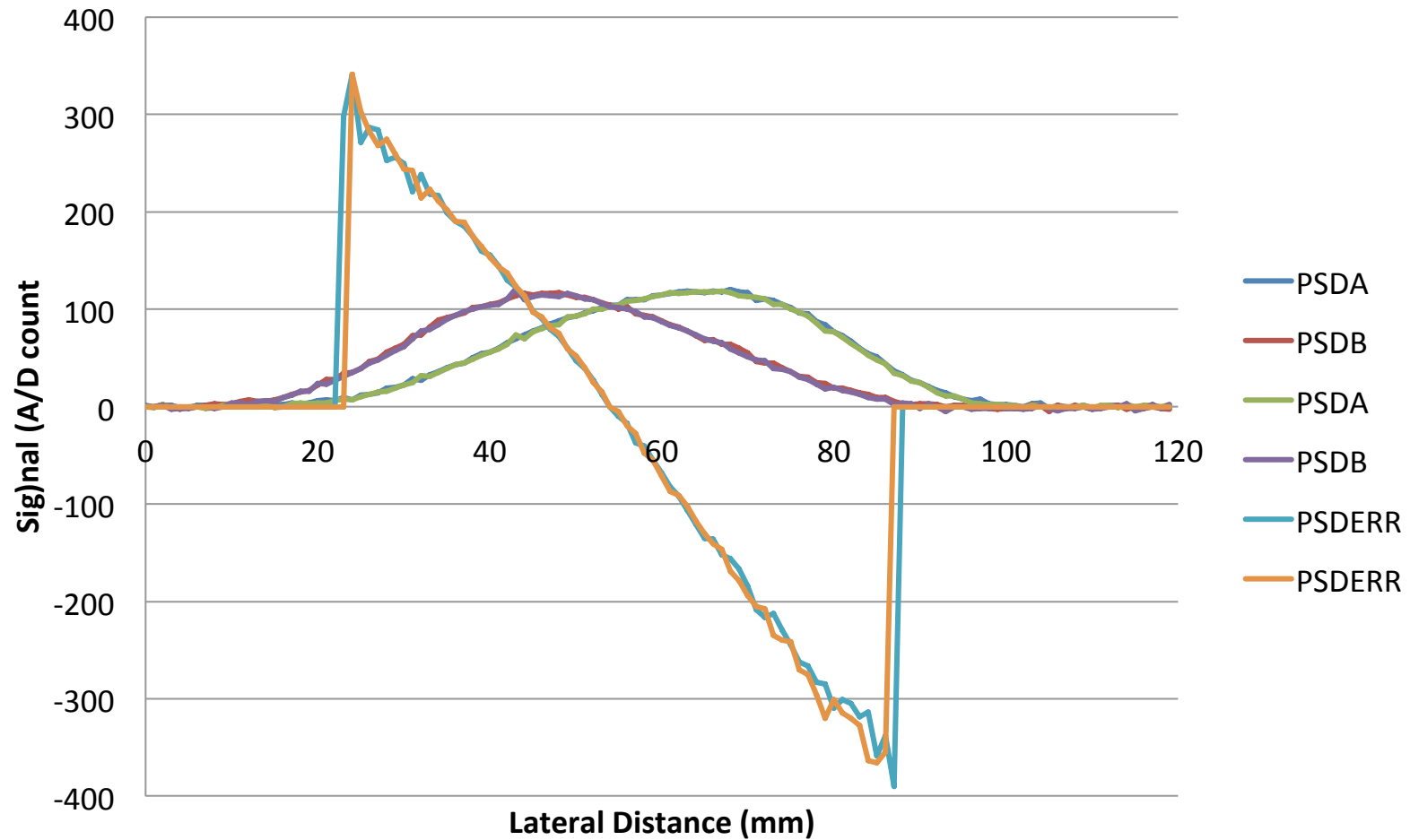
Jehu 2 PSD signal



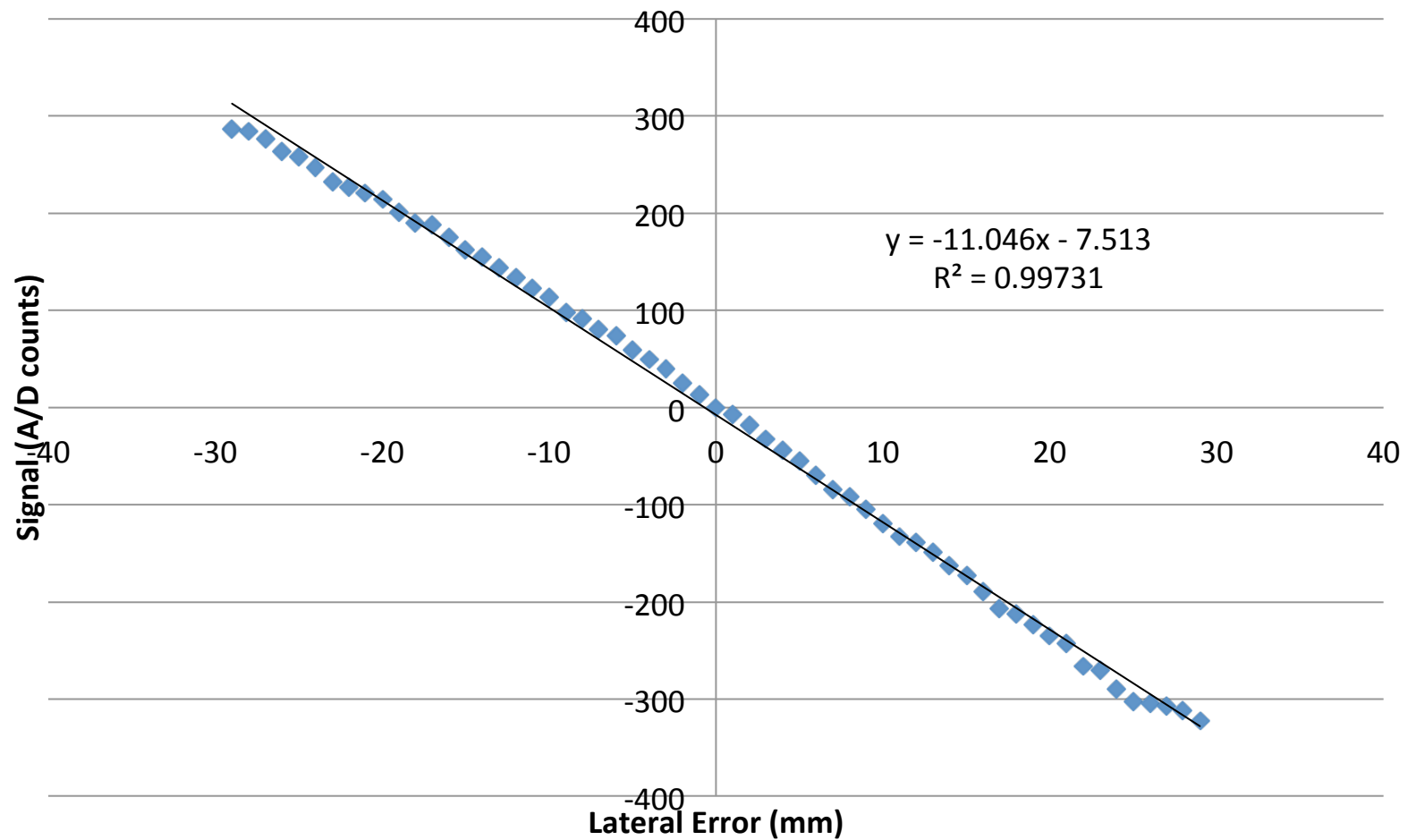
Offset and Amplitude Corrected



$1024 * \text{PSDB} / (\text{PSDA} + \text{PSDB}) - 512$

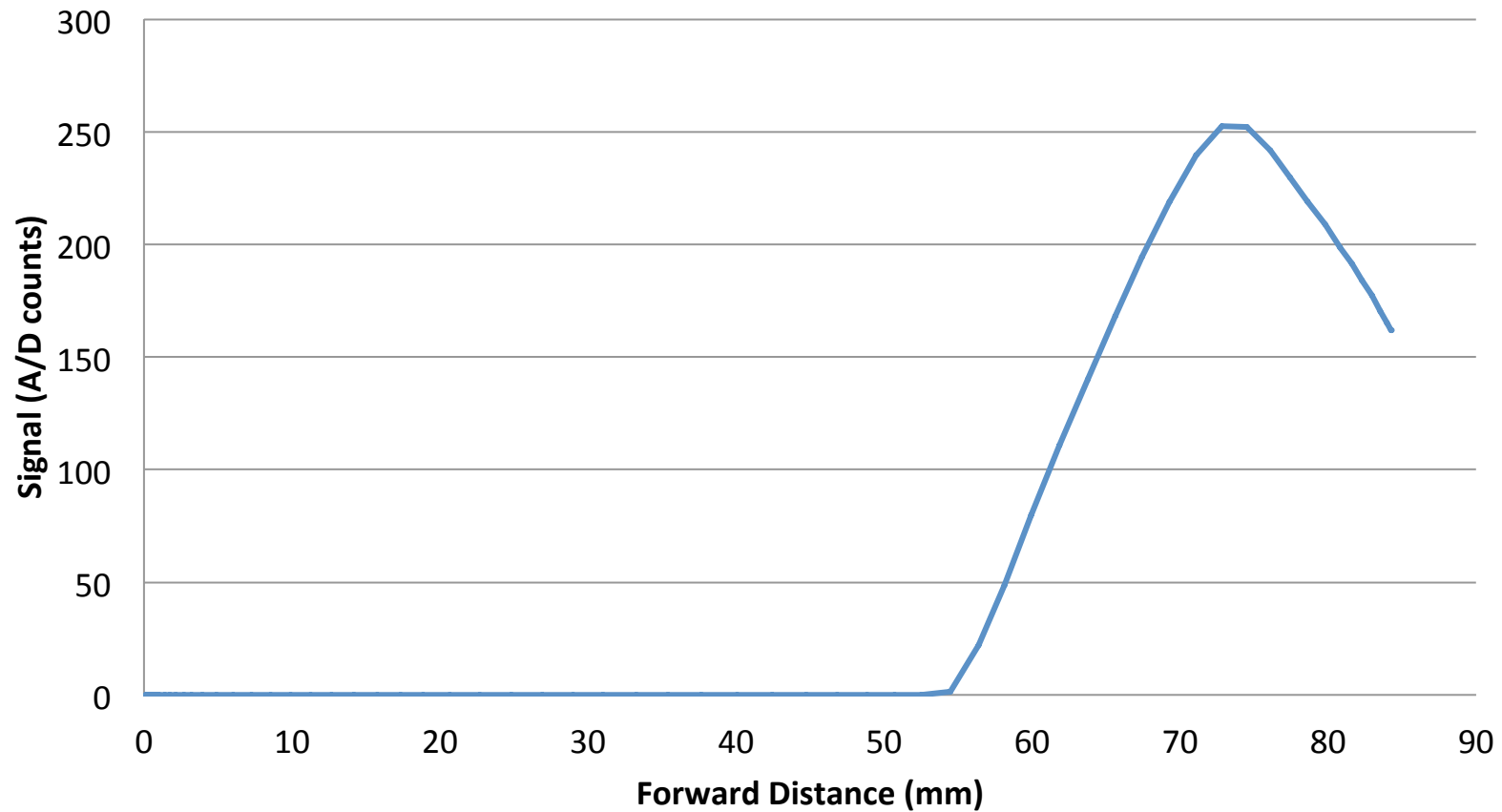


Sensor Gain and Linearity



Intensity vs. Distance

Peak = 73.0 mm (2.87")

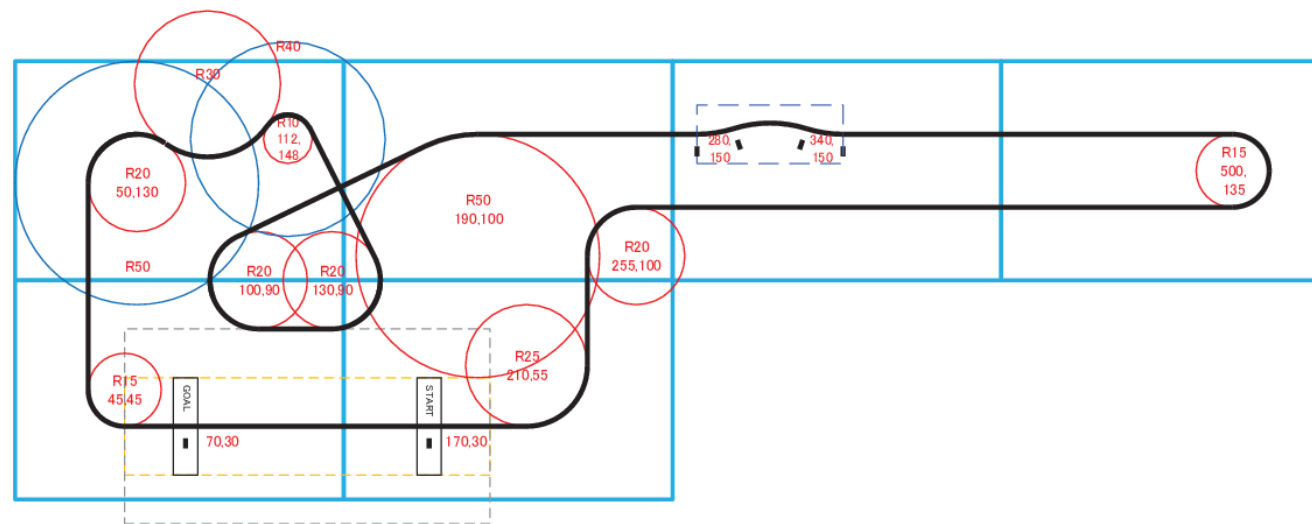


All Japan 2017

2017年全日本大会ロボットレース競技予選

全長13.0m
(昨年13.3m)

↑観覧席
←観覧席 審査員席→
↓競技者控え



←「R50_60cm」テンプレートを使用



All Japan 2017



End

