

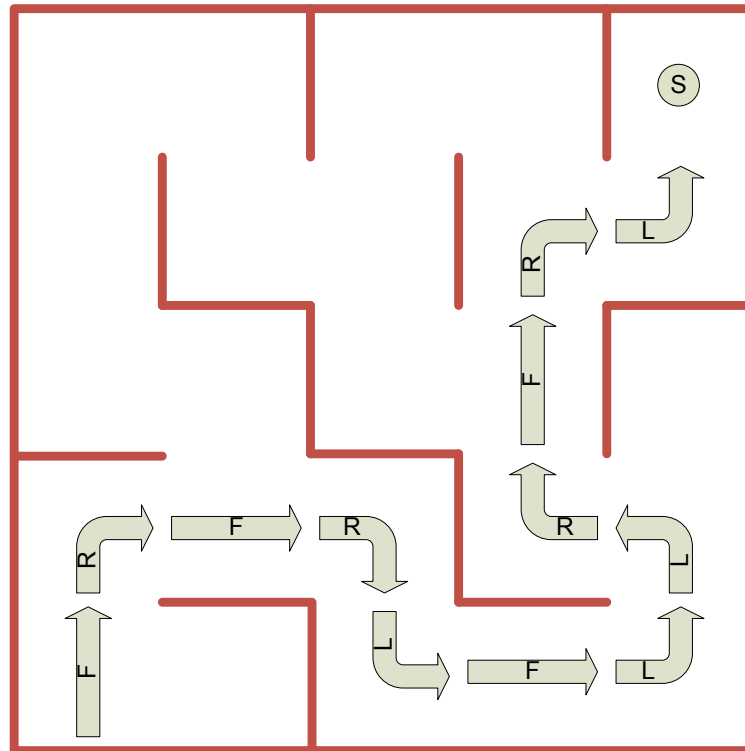
The Butterfly Machine

Diagonal Pathfinding
in a
maze of little twisty passages

Peter Harrison 2014

A Maze Path Example

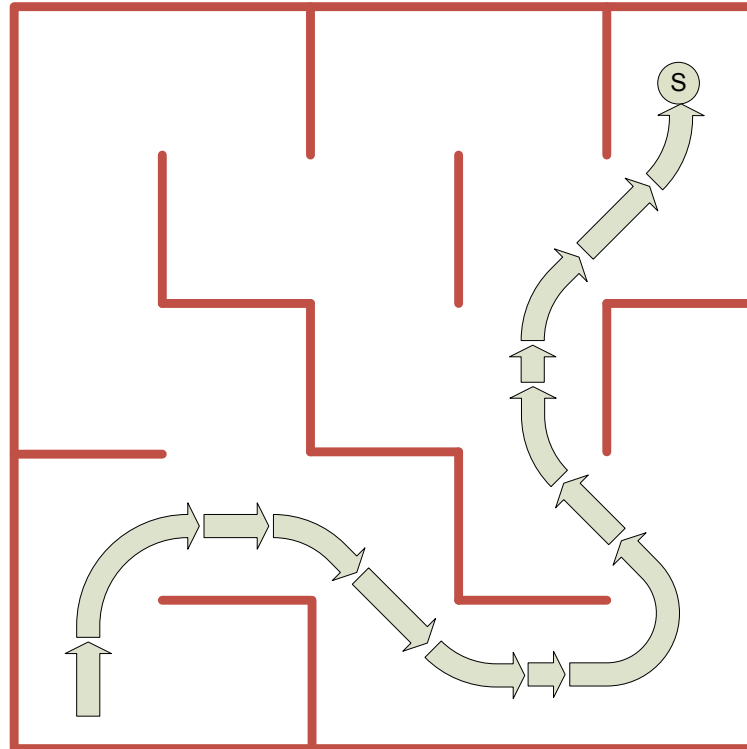
FRFRLFLLRFRLS



In-place turns, no run length encoding

A Maze Path Example

FRFLFLLRFRLS



Smooth turns, concatenated straights

**FWD01
 SS90SR
 FWD02
 SD45R
 DIA02
 DS45L
 FWD02
 SD135L
 DIA02
 DS45R
 FWD02
 SD45R
 DIA02
 DS45L
 FWD01
 STOP**

Substring Searches

- Orthogonal path is a string
 - “FFRFFFLRFLLFS”
- Run length encode
- Look for patterns in priority order

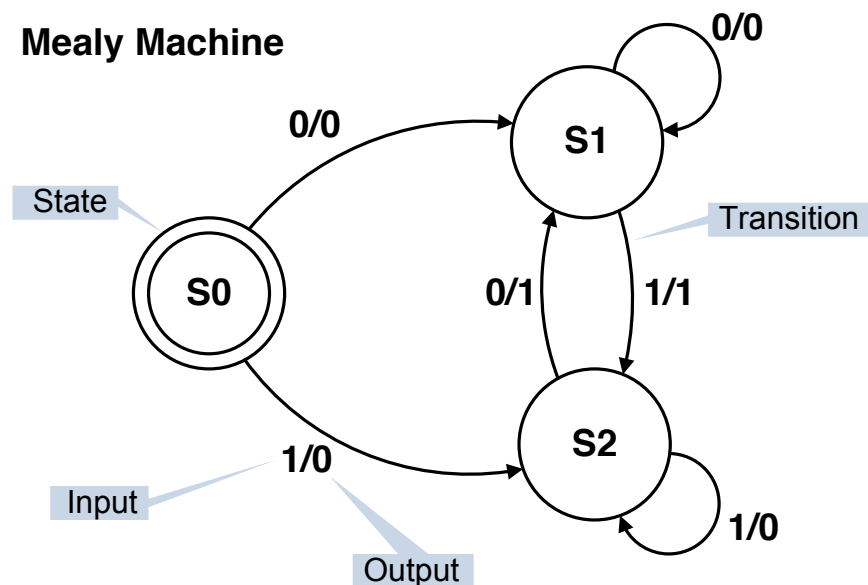
```
c0 = commandList[cptr + 0];
c1 = commandList[cptr + 1];
c2 = commandList[cptr + 2];
c3 = commandList[cptr + 3];
c4 = commandList[cptr + 4];
c5 = commandList[cptr + 5];
c6 = commandList[cptr + 6];
if ( (c1 > FWD1) && (c1 < FWD16)) {
    tempList[tptr++] = c1;
    cptr = cptr + 1;
} else if ( (c0 < FWD16) && (c1 == 'R') && (c2 == FWD1) && (c3 == 'L')) {
    tempList[tptr++] = SD45R;
    x = DIA1;
    cptr = cptr + 1;
} else . . .
```

Scan and Look Ahead

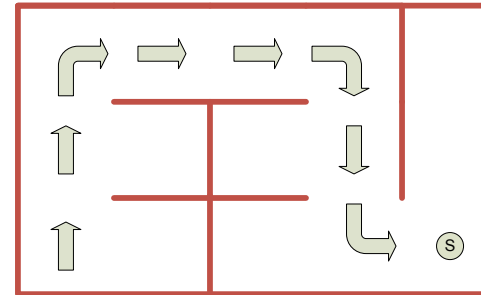
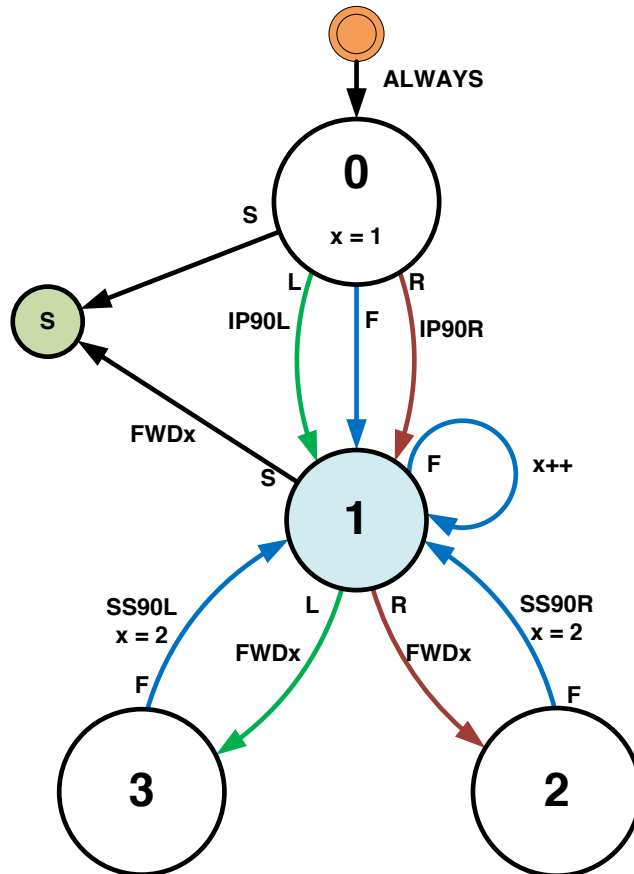
- Translate characters as found
- Look ahead as needed
- Retain straight vs diagonal state
- A single 'F' is unambiguous
- Turns need look ahead to translate

Translate as Found

- Effect of commands depends on history
- Classic case for a state machine
- Example



Orthogonal Machine



FFRFFRFLS

FWD02

SS90R

FWD03

SS90R

FWD02

SS90L

FWD01

STOP

Orthogonal Machine Implementation

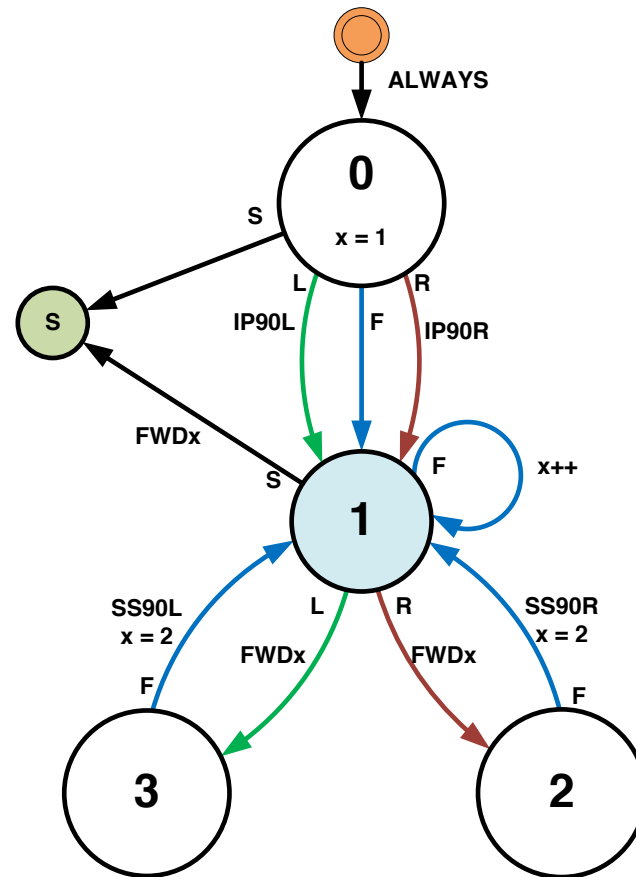
- Simple but lengthy switch/case statements

```
void orthoMachine(char * s) {
    int state = 0;
    unsigned char c;
    while (state != 11) {
        c = *s++;                // fetch next instruction
        switch (state) {
            case 0:                // entry point
                break;
            case 1:                //F+
                break;
            case 2:                //F+R
                break;
            case 3:                //F+L
                break;
            case 10:               // exit point
                emit(CMD_STOP);
                state = 11;
                break;
            default:               // catch-all error state
                emit(CMD_ERROR);
                state = 11;
                break;
        }
    }
}
```


Orthogonal Machine Implementation

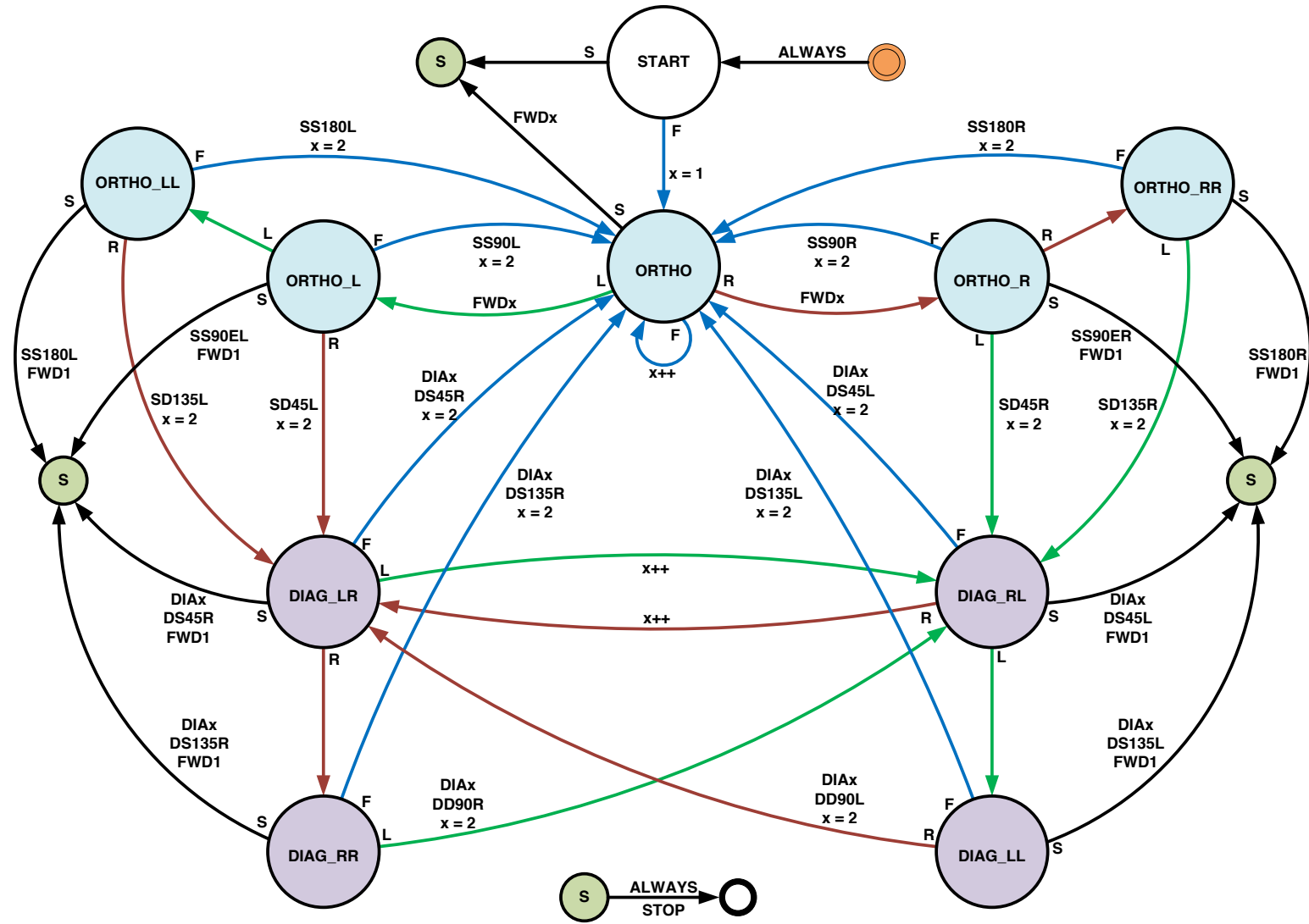
- State 1 code

```
case 1:  
  if (c == 'F') {  
    x++;  
  } else if (c == 'L') {  
    emit(FWD0 + x);  
    state = 3;  
  } else if (c == 'R') {  
    emit(FWD0 + x);  
    state = 2;  
  } else if (c == 'S') {  
    emit(FWD0 + x);  
    state = 10;  
  } else {  
    state = 11;  
  }  
  break;
```



MAZE PATHFINDER STATE MACHINE

CONVERT ORTHOGONAL PATH TO DIAGONALS



Test Driven Development

- Problems:
 - State machine is complex
 - Short sequences not too hard
 - Real mazes forbidding with many paths
- Solutions:
 - Write a generic test function
 - Write simple tests from existing mouse code
 - Write code to make each test pass
 - Only progress when tests pass

Test Data

- Start simple, add complexity gradually
- Test data from existing mouse code (42 test pairs so far)

```
typedef struct {
    char input[MAX_LEN];
    COMMAND output[MAX_LEN];
} testPair_t;

testPair_t testPairs[] = {
    // basic straights
    {"S",      {STOP}},
    {"FS",     {FWD1, STOP}},
    {"FFS",    {FWD2, STOP}},
    // simple 90 degree turns
    {"FRS",    {FWD1, SS90ER, FWD1, STOP}},
    {"FLS",    {FWD1, SS90EL, FWD1, STOP}},
    {"FRFS",   {FWD1, SS90SR, FWD2, STOP}},
    {"FLFS",   {FWD1, SS90SL, FWD2, STOP}},
    {"FFRFS",  {FWD3, SS90SR, FWD2, STOP}},
}
```

Test Process

- Test Function
 - Gets input string and expected output
 - Converts input to calculated output
 - Success if calculated matches expected
- Test Process
 - Add **one** set of test data
 - Test all the test data
 - Write code to make the tests pass

Performance

- Original code made three passes to get from orthogonal list to a final instruction sequence
- Substring comparisons potentially costly
- New code takes a single pass
- Code size down: 3114 bytes to 1348 bytes
- Run time down: 42000 cycles to 8500 cycles
- Easier to modify
- Still a 240 line function though
- There may be better implementation methods

Results

- Output from existing mouse from actual maze data matches new routine
- Development method assures correspondence with existing code
- No guarantee existing code is correct
- Untried in a maze

THANK YOU